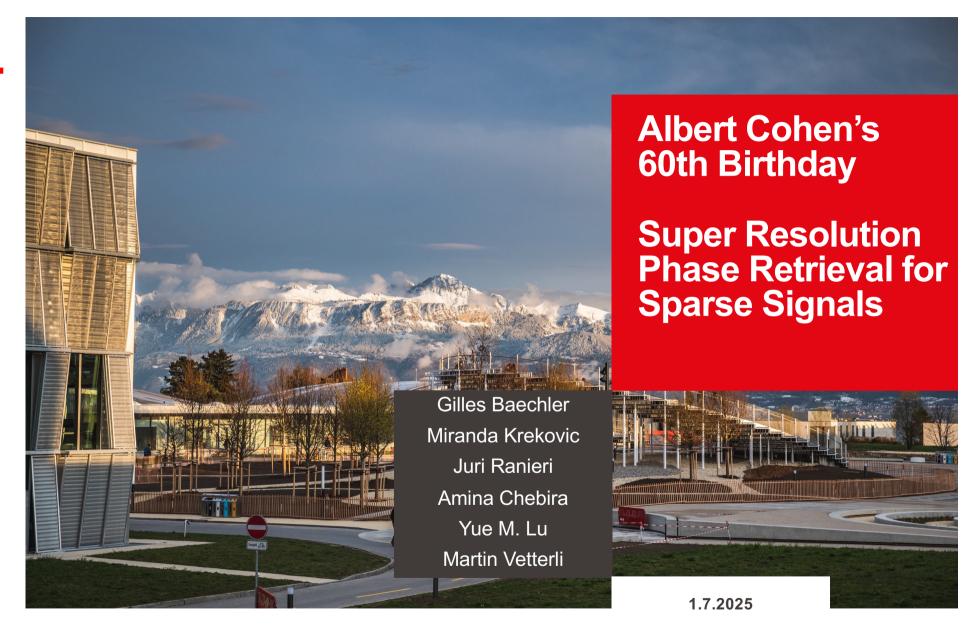
# **EPFL**



 École polytechnique fédérale de Lausanne



# **OVERVIEW**

- 1. Albert Cohen
- 2. Our 2019 paper revisited
- 3. Super Resolution Phase Retrieval for Sparse Signals
- 4. Where to go from here
- 5. Conclusion

#### THESE

POUR L'OBTENTION DU TITRE DE DOCTEUR
EN ANALYSE NON LINEAIRE APPLIQUEE

Sujet.

ONDELETTES, ANALYSES MULTIRESOLUTIONS
ET TRAITEMENT NUMERIQUE DU SIGNAL

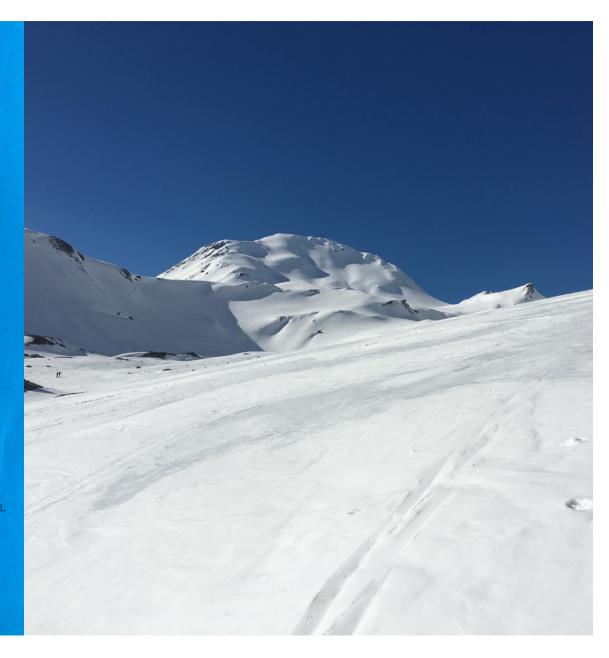
Candidat. Albert COHEN

Directeur de recherche. Yves MEYER

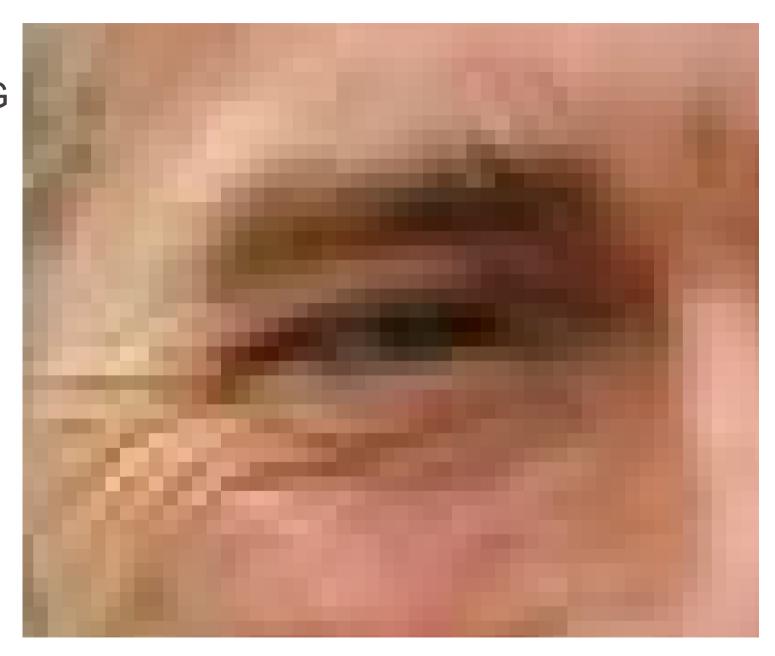
Jury:

Président: Rapporteur: Rapporteur: Monsieur Ivar EKELAND Monsieur Jean-Pierre CONZE Monsieur Jean-Michel MOREL Monsieur Michel GRANGER Monsieur Pierre-Louis LIONS Monsieur Yves MEYER

Année de soutenance : 1990



# Albert Cohen coded in JPEG







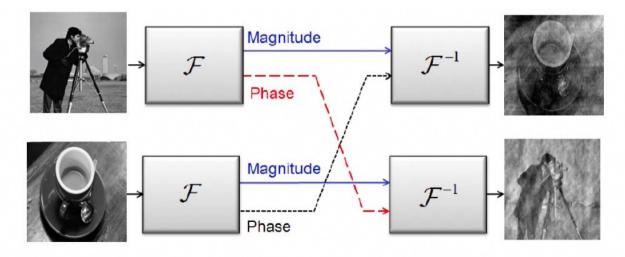
# **OVERVIEW**

- 1. Albert Cohen
- 2. Our 2019 paper revisited
- 3. Super Resolution Phase Retrieval for Sparse Signals
- 4. Where to go from here
- 5. Conclusion

4839

# Super Resolution Phase Retrieval for Sparse Signals

Gilles Baechler, Student Member, IEEE, Miranda Kreković, Student Member, IEEE, Juri Ranieri, Amina Chebira, Yue M. Lu, Senior Member, IEEE, and Martin Vetterli, Fellow, IEEE



Phase Retrieval Process: Recovering signal from magnitude-only measurements

Phase retrieval

### **EPFL**

# State of the art, 6 years later...

MV: I work on phase retrieval from Fourier magnitude, can you help me?

Mistral Le Chat output:

- 1. Gerchberg-Saxton Algorithm
- 2. Fienup Algorithm
- 3. Convex Relaxation
- 4. Deep Learning
- 5. Compressed Sensing

I am interested in the case when the signal is sparse in time domain, like a sequence of Dirac pulses at arbitrary locations

#### M: Example: Compressed Sensing Approach

1. Formulate the Problem:

$$\min \|x\|_1$$
 subject to  $|Fx| = b$ 

where x is the sparse signal, F is the Fourier transform matrix, and b is the measured Fourier magnitude.

ADMM etc

Phase retriev

# State of the art, 6 years later...

MV: Let me formulate the problem: ... our algorithm estimates the signal on a continuous domain, which makes it the first of its kind.

M:

• **Signal Model**: Clearly define the signal model, assuming it is sparse in the time domain. For example, the signal x(t) can be represented as:

$$x(t) = \sum_{k=1}^K a_k \delta(t-t_k)$$

where  $a_k$  are the amplitudes,  $t_k$  are the locations of the Dirac pulses, and K is the number of pulses.

#### Three-Stage Algorithm

Stage 1: Super-Resolution of the Auto-Correlation Function

- Finite Rate of Innovation (FRI) Sampling: Use FRI sampling theory to super-resolve the auto-correlation function from a limited number of samples. This involves:
  - Sampling: Acquire samples of the auto-correlation function at a rate sufficient to capture
    the innovation rate of the signal.
  - Reconstruction: Use reconstruction algorithms to recover the continuous autocorrelation function from the samples.

etc....

### **EPFL**

### State of the art, 6 years later...

MV: is there previous work I can cite, and by which authors?

M: Certainly... the usual suspects, Gerchberg-Saxton, Fienup, convex relaxation, compressed sensing, FRI etc and...

 Goy, A. P., Liu, C., & Vetterli, M. (2019). "Deep Learning for Phase Retrieval." IEEE Signal Processing Magazine, 36(4), 18-39.



MV: I think there is a paper entitled "Super Resolution Phase Retrieval for Sparse Signals" which could be relevant?



Yes, the paper titled "Super Resolution Phase Retrieval for Sparse Signals" is indeed relevant to your work. This paper focuses on the phase retrieval problem for sparse signals and proposes methods to achieve super-resolution. Here are the details:

#### **Paper Details**

- Title: Super Resolution Phase Retrieval for Sparse Signals
- Authors: Yonina C. Eldar, Shahar Nevo, and Eran Treister
- Publication: IEEE Transactions on Signal Processing, 2018





# **OVERVIEW**

- 1. Albert Cohen
- 2. Our 2019 paper revisited
- 3. Super Resolution Phase Retrieval for Sparse Signals
- 4. Where to go from here
- 5. Conclusion

Martin Vetterli

# **EPFL** Sparse phase retrieval: problem formulation

How to reconstruct a **sparse** signal

$$f(x) = \sum_{k=1}^{K} c_k \delta(x - x_k)$$

from the **magnitude** of its Fourier transform  $|F(\omega)|^2$  ?

### **Applications**:

- X-ray crystallography, diffractive imaging, ...
- Speckle imaging
- Blind deconvolution and channel estimation
- Spectral factorization

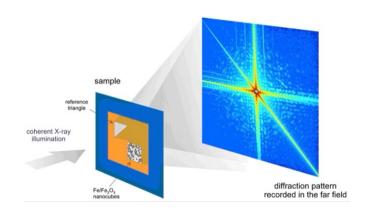
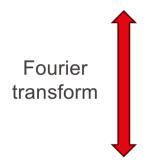


Fig credit: Stanford SLAC

### **EPFL** Problem formulation in the Fourier domain

#### K-sparse signal

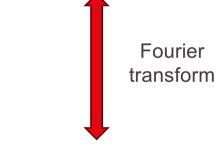
$$f(x) = \sum_{k=1}^{K} c_k \delta(x - x_k)$$



$$F(\omega) = \sum_{k=1}^{K} c_k e^{-j\omega^{\top} x_k}$$

#### **Auto-correlation function**

$$a(x) = \sum_{k=1}^{K} \sum_{\ell=1}^{K} c_k c_\ell \delta(x - (x_k - x_\ell))$$





$$|F(\omega)|^2$$

# Phase refrieva

# **EPFL** A proposed three-stage approach

#### Equivalent problem:

Estimate the **support**  $\{x_k\}_{k\leq K}$  and **weights**  $\{c_k\}_{k\leq K}$  from (samples) of the Fourier transform of the auto-correlation function (ACF)

**Step 1**: we leverage the **finite rate of innovation** sampling theory to super-resolve the ACF from a limited number of samples

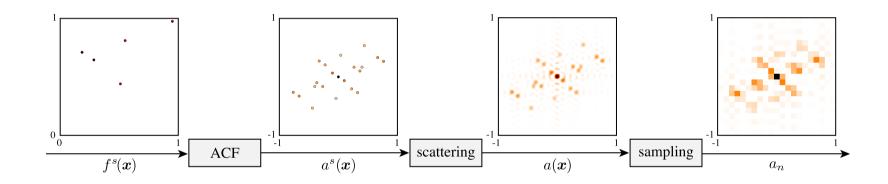
**Step 2**: we design a greedy algorithm that identifies the locations of a sparse solution given the super-resolved ACF

**Step 3**: we recover the amplitudes of the atoms given their locations and the measured autocorrelation function.

Martin Vetterli

# Step 1: super-resolve the ACF via finite-rate-of-innovation

**Observation**: The ACF  $a(x) = \sum_{k=1}^K \sum_{\ell=1}^K c_k c_\ell \delta \big( x - (x_k - x_\ell) \big)$  is still a sparse function, containing  $K^2 - K + 1$  atoms.



#### Finite-rate-of-innovation sampling [Vetterli, Marziliano, Blu, 2002]

- Super-resolution techniques from limited samples, with connections to spectral analysis techniques (e.g. Prony's method)
- Sample complexity for ACF:  $\mathcal{O}(K^2)$  samples [Pan, Blu, and Vetterli, 2018]

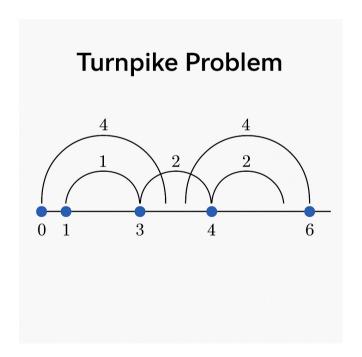
# Step 2: estimate the locations of the atoms

#### **Problem formulation:**

Estimate the locations of the atoms  $x_1, x_2, \dots, x_K$  from the set of **pairwise differences**  $\mathcal{X} = \{x_k - x_\ell\}_{k,\ell}$ 

**Challenge:** the difference set  $\mathcal{X}$  is **unlabeled** 

Skiena and Sundaram, "Reconstructing sets from interpoint distances," in *Proceedings of the Sixth Annual ACM-SIAM Symposium on Discrete Algorithms (SODA)*, 1995.



Phase retrieval

# Step 2: estimate the locations of the atoms

# in Vetterli

### A greedy approach:

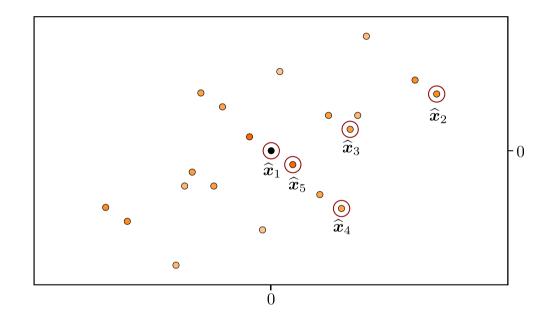
#### Algorithm 1: Support Recovery.

```
Input: A set of N = K^2 - K + 1 differences \widetilde{\mathcal{D}} = \{\widetilde{\boldsymbol{d}}_n\}_{n=1}^N ordered by their norms
```

**Output:** A set of K points  $\widehat{\mathcal{X}}$  such that their pairwise differences generate  $\widehat{\mathcal{D}}$ 

$$\begin{split} \widehat{\mathcal{X}}_2 &= \{\mathbf{0}, \widetilde{\boldsymbol{d}}_N\} \\ \mathcal{P}_2 &= \widetilde{\mathcal{D}} \setminus \{\widetilde{\boldsymbol{d}}_1, \widetilde{\boldsymbol{d}}_N\} \\ \mathbf{for} \ k &= 2, \dots, K-1 \ \mathbf{do} \\ \widehat{\boldsymbol{x}}_{k+1} &= \operatornamewithlimits{argmin}_{\boldsymbol{p} \in \mathcal{P}_k} \sum_{\widehat{\boldsymbol{x}} \in \widehat{\mathcal{X}}_k} \min_{\widetilde{\boldsymbol{d}} \in \widetilde{\mathcal{D}}} \left\| \boldsymbol{p} - \widehat{\boldsymbol{x}} - \widetilde{\boldsymbol{d}} \right\|^2 \\ \widehat{\mathcal{X}}_{k+1} &= \widehat{\mathcal{X}}_k \cup \widehat{\boldsymbol{x}}_{k+1} \\ \mathcal{P}_{k+1} &= \mathcal{P}_k \setminus \widehat{\boldsymbol{x}}_{k+1} \\ \mathbf{end} \ \mathbf{for} \end{split}$$

end for return  $\widehat{\mathcal{X}}_K$ 



# **EPFL** Step 3: recover the amplitudes of the atoms

#### **Auto-correlation function**

$$a(x) = \sum_{k=1}^{K} \sum_{\ell=1}^{K} c_k c_{\ell} \delta(x - (x_k - x_{\ell}))$$

### Amplitude recovery:

Estimate  $c_1, \ldots, c_K$  from  $c_k c_\ell$  for  $k \neq \ell$ 

### **Equivalent formulation:**

Estimate the missing diagonal entries of a rank-one symmetric matrix  $C=(c_ic_j:1\leq i,j\leq K)$ 

A matrix completion problem!

*Matrix completion:* Estimate the missing diagonal entries of a rank-one symmetric matrix

$$C = (c_i c_j : 1 \le i, j \le K)$$

**A closed-form solution:** Let  $\ell = [\log(c_1), \ldots, \log(c_K)]^{\top}$ 

Define 
$$L_{ij} = \begin{cases} \log(C_{ij}) = \log(c_i) + \log(c_j) & \text{for } i \neq j \\ 0 & \text{otherwise} \end{cases}$$

then 
$$\ell = \frac{1}{K-2} \left( L \cdot \mathbb{1} - \frac{\mathbb{1}^{\top} L \mathbb{1}}{2(K-1)} \mathbb{1} \right)$$

#### Performance analysis and phase transitions **EPFL**

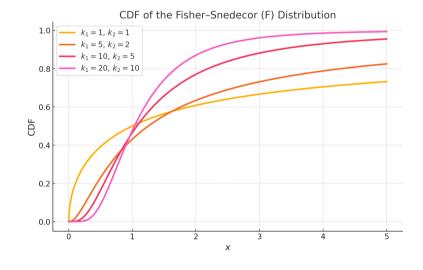
Probability of successfully reconstructing K atoms at noise level  $\sigma$ 

$$P(\sigma, K) = \prod_{k=2}^{K-1} \left[ 1 - \left( 1 - F\left( \frac{3\sigma^2 + 1/2}{3\sigma^2}, k, k \right)^{a_k(K)} \right)^{K-k} \right]$$

where

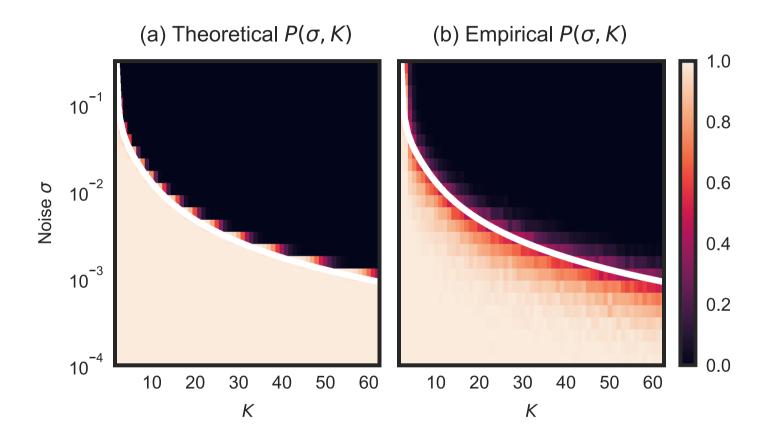
$$a_k(K) = (K^2 - K + 1)^k (K^2 - 2K + 1)$$

 $F(x, k_1, k_2)$ : Cumulative distribution function of the Fisher-Snedecor distribution



Caveat: derived with several independence assumptions that are not fully justified

# EPFL Performance analysis and phase transitions

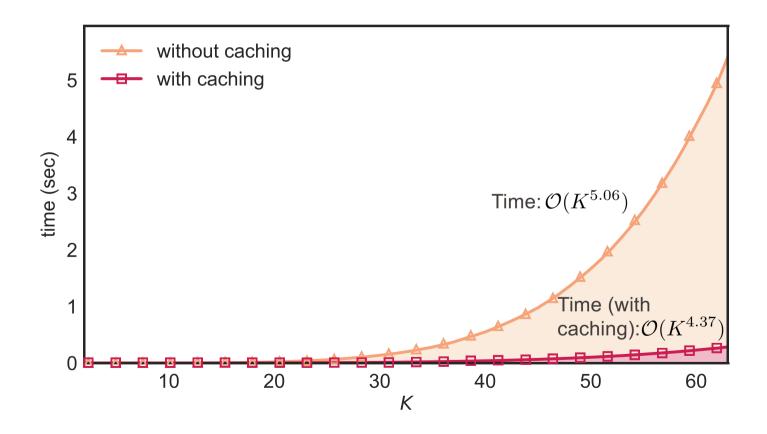


*Caveat*: derived with several independence assumptions that are not fully justified, but they seem to hold in practice ... (*see discussions*)

# **EPFL** Complexity analysis

Phase retrieval

Computational complexity: worst case  $\mathcal{O}(K^6)$ 



# **EPFL** Comparison with the state-of-the-art

Charge flipping: a standard benchmark algorithm in crystallography

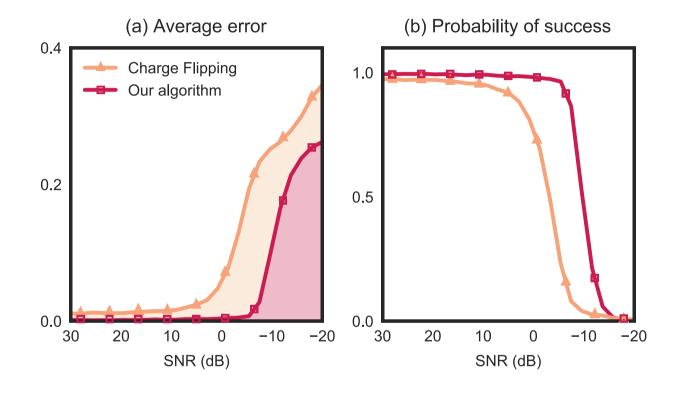
#### Fourier domain:

$$F_{n+1}(\omega) = |F_{\text{obs}}(\omega)| \frac{F_n(\omega)}{|F_n(\omega)|}$$

### Space domain:

$$f_{n+1}(x) = \begin{cases} f_n(x), & \text{if } f_n(x) > \delta \\ -f_n(x), & \text{if } 0 < f_n(x) < \delta \\ 0, & \text{if } f_n(x) < 0 \end{cases}$$

# **EPFL** Comparison with the state-of-the-art



K = 5 atoms with locations chosen uniformly from [0, 1] Number of DFT coefficients = 200





# **OVERVIEW**

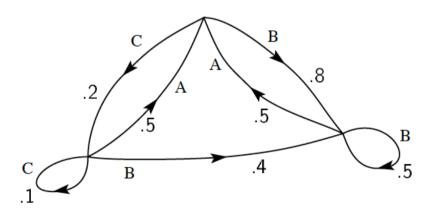
- 1. Albert Cohen
- 2. Our 2019 paper revisited
- 3. Super Resolution phase retrieval for sparse signals
- 4. Where to go from here
- 5. Conclusion

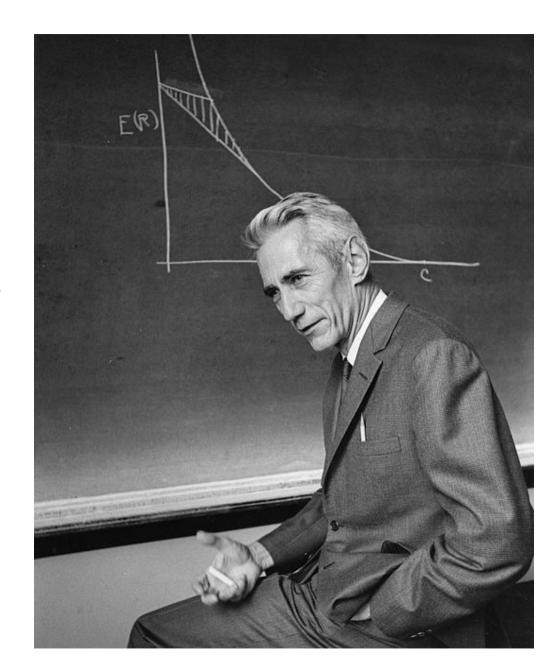
# **EPFL** A bit of history: Al and IT

#### C.E. Shannon

A Mathematical Theory of Communication (1948) Small Language Model:

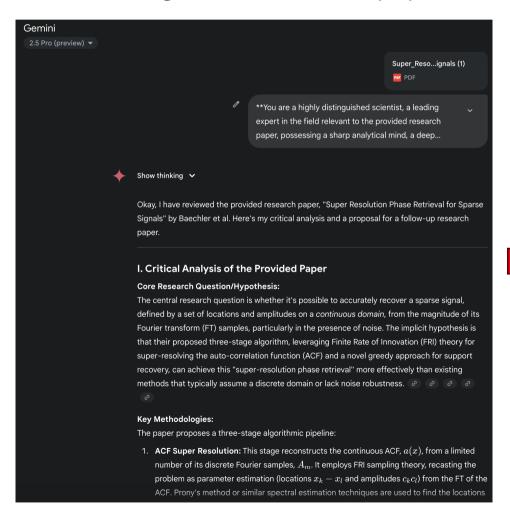
THE HEAD AND IN FRONTAL ATTACK ON AN ENGLISH WRITER THAT THE CHARACTER OF THIS POINT IS THEREFORE ANOTHER METHOD FOR THE LETTERS THAT THE TIME OF WHO EVER TOLD THE PROBLEM FOR AN UNEXPECTED





### What does AI tell us to do now?

### Creating a new research paper with a few prompts in Gemini (Baechler 2025)



#### PHASE SHIFT: ADAPTIVE SUPER-RESOLUTION FOR ROBUST PHASE RETRIEVAL

Jav Mini

Department of Signal Processing and Inverse Problems, Swiss Federal Institute of Technology (ETH Zurich), Switzerland

#### ARSTRACT

Phase retrieval (PR) is a critical inverse problem across diverse scientific and engineering domains, particularly for sparse signals defined on a continuous domain. While recent advancements have enabled super-resolution PR, existing methods often struggle with non-ideal noise characteristics, non-sinc scattering kernels, and inherent ambiguities arising from specific geometric configurations of sparse points. Furthermore, a fundamental trade-off between reconstruction quality and computational complexity limits scalability for large-scale problems. This paper presents a novel, adaptive, and robust framework for super-resolution phase retrieval. Our methodology introduced advanced statistical noise modeling and kernel learning for the auto-correlation function (ACF) super-resolution stage, coupled with a configurationaware, robust greedy algorithm for support recovery that dynamically adapts to challenging point geometries. We also developed a hybrid quality-complexity optimization strategy, leveraging parallelization and deep learning-based surrogate models to enhance scalability. Simulated results demonstrated significant improvements in reconstruction accuracy under realistic noise, enhanced robustness to geometric ambiguities, and superior scalability for larger numbers of sparse elements. This work represents a substantial step towards deploying continuous-domain phase retrieval in demanding applications like cryo-electron microscopy and advanced op-

Index Terms— Phase retrieval, super-resolution, sparse signals, robust estimation, machine learning, inverse problems, finite rate of innovation.

#### 1. INTRODUCTION

The problem of phase retrieval (PR), where one seeks to reconstruct a signal from the magnitude of its Fourier Transform (FT), is ubiquitous in fields ranging from X-ray crystallography and optical imaging to astronomy and communications [1–3]. The inherent ill-posedness of PR necessitates the incorporation of prior information or constraints to achieve a unique and accurate solution. A particularly compelling prior is signal sparsity, where the signal can be represented as a finite sum of a few atomic components [4,5].

Traditional PR algorithms, such as Charge Flipping [6], typically operate on discrete grids, leading to inherent discretization errors and limiting the achievable resolution. Recent groundbreaking work has introduced algorithms capable of super-resolution phase retrieval for sparse signals on a continuous domain, leveraging Finite Rate of Innovation (FRI) sampling theory [7, 8]. These methods promise theoretically infinite resolution, constrained only by measurement noise. The work by Baechler et al. [8] (hereafter referred to as "the original paper") notably demonstrated a three-stage pipeline that achieves robust continuous-domain recovery in the presence of significant noise, outperforming discrete-grid methods like Charge Flipping.

Despite these advancements, several critical limitations hindered the widespread practical deployment of continuousdomain sparse PR. Firstly, the theoretical performance analysis and algorithmic design often relied on idealized assumptions regarding noise characteristics (e.g., i.i.d. Gaussian noise) and scattering kernel functions (e.g., ideal sinc functions) [8]. In real-world scenarios, noise is complex, non-Gaussian, and correlated, and scattering functions are rarely ideal, leading to performance degradation. Secondly, the original paper identified that certain geometric configurations of sparse points intrinsically led to higher reconstruction errors, even with noise resilience improvements [8]. The greedy support recovery algorithm did not inherently adapt to these "challenging patterns," resulting in reduced reliability. Finally, a fundamental trade-off existed between applying denoising strategies (which improve quality) and caching mechanisms (which improve computational speed) [8]. Furthermore, while polynomial, the computational complexity of  $O(K^{4.37})$  for K sparse elements remained a bottleneck for very large-scale problems, such as those encountered in cryo-electron microscopy of complex macromolecules.

This paper presents a novel, adaptive, and robust framework for super-resolution phase retrieval that directly addresses these limitations. Our contributions are threefold:

 We developed a robust ACF super-resolution stage that explicitly models and compensates for non-Gaussian/cor

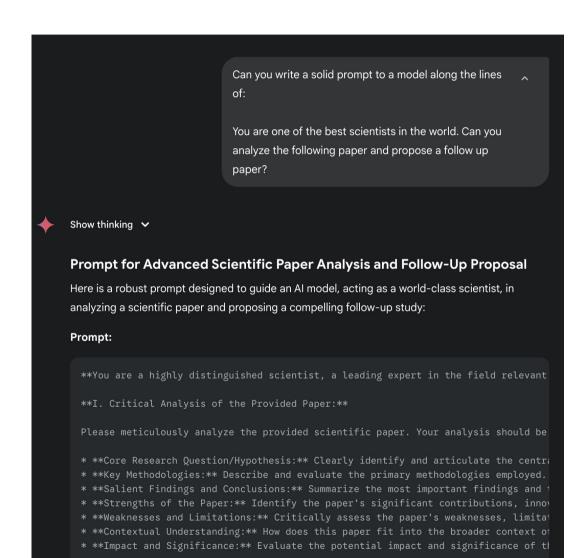
This work is supported by the European Research Council (ERC) Advanced Grant "PHASE-SHIFT" under grant agreement No. 101054321 and the Swiss National Science Foundation (SNSF) project "ROBUST-FRI".

#### Creating a paper with Gemini **EPFL**

#### Gemini 2.5 Pro with Deep Research:

- 1 model to craft the prompts
- 1 model to perform the research
- Overall, it took 1-2 hours to create a full paper

Meta prompting (because writing your own prompts is tedious ;-))



# **EPFL** Creating a paper with Gemini

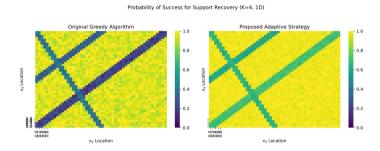
#### Step by step:

- 1. Ask Gemini (in Deep Research mode) to analyze our TSP paper and write a research plan for a follow up paper.
- 2. Generate latex code and fill in an IEEE .tex template.
- 3. There were 3 placeholder figures in the generated .tex, ask it to generate the python code to create the figures.
- 4. Generate the figures within a colab.
- 5. Last, one more pass to improve the manuscript.

#### Human intervention:

- There were only a few minimal errors in the generated .tex and .py files:
  - o The model got all references correctly, except for one.
  - The python and tex code were flawless, except for:
    - 1 mistake regarding the pyplot axes.
    - 1 issue with the latex document class that was causing rendering errors





# **EPFL** Quick overview: Limitations of Original Work

#### Key Limitations in Baechler et al. [8]

#### **Idealized Noise Assumptions**

- · Assumed i.i.d. Gaussian noise
- Real-world noise is complex, non-Gaussian, and correlated
- Performance degradation in practical scenarios

#### **Geometric Ambiguities**

- Certain point configurations lead to higher errors
- Greedy algorithm not adaptive to "challenging patterns"
- Reduced reliability for specific geometries

#### **Non-Sinc Scattering Kernels**

- · Assumed ideal sinc function as scattering kernel
- · Scattering functions rarely ideal in practice
- · Limited accuracy in real applications

#### **Computational Complexity**

- Trade-off between quality (denoising) and speed (caching)
- O(K4.37) complexity for K sparse elements
- Bottleneck for large-scale problems (e.g., cryo-EM)

# **EPFL** Three Key Contributions

#### 1 Robust ACF Super-Resolution

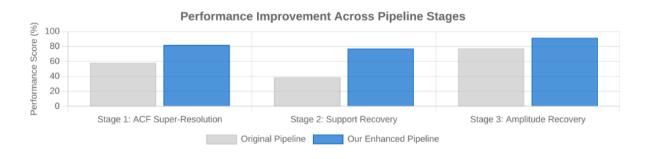
Advanced statistical noise modeling and kernel learning for the auto-correlation function (ACF) super-resolution stage, enhancing accuracy under realistic conditions with non-Gaussian noise and non-ideal kernels.

#### Adaptive & Robust Support Recovery

Configuration-aware, robust greedy algorithm for support recovery that dynamically adapts to challenging point geometries, improving reliability in ambiguous scenarios.

#### **4** Hybrid Quality-Complexity Optimization

Adaptive denoising/caching strategy with parallelization and deep learning-based surrogate models to significantly improve scalability for large K while maintaining high reconstruction quality.

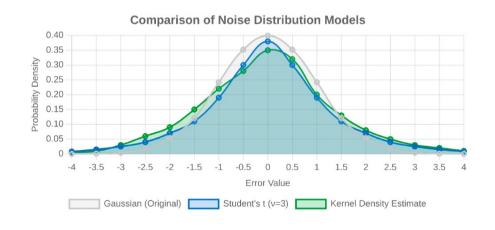


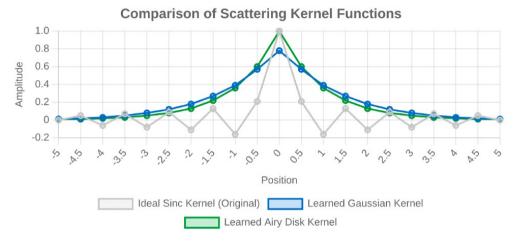
# Robust ACF Super Resolution

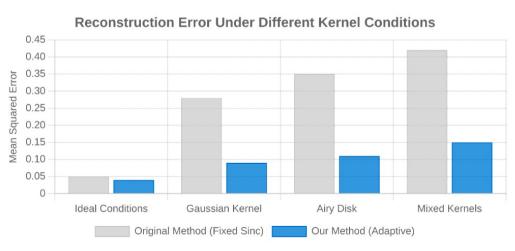
# Vetterli

#### Key Challenges

- · Non-Gaussian and correlated noise
- Non-ideal scattering kernels
- Propagation of errors to later stages







### **EPFL**

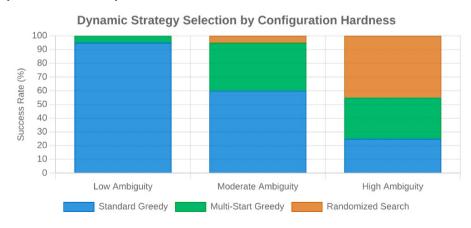
### Adaptive Support Recovery: Robust Cost Functions

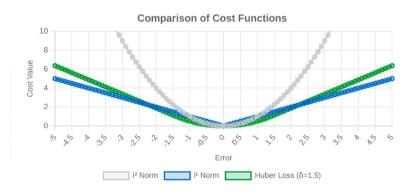
#### Different cost functions

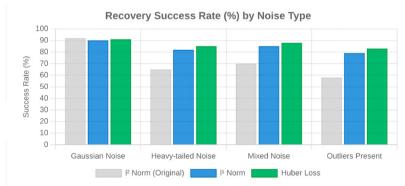
- 12
- 11
- Huber loss

#### Enhanced greedy algorithm

- Initialize with 0 and largest norm difference
- Compute candidate points P from current solution  $\hat{X}$
- Evaluate **configuration hardness metric** for  $\tilde{D}$  and  $\hat{X}$
- Dynamically select strategy based on hardness metric
- Add next point using robust cost function minimization
- Repeat until K points are recovered







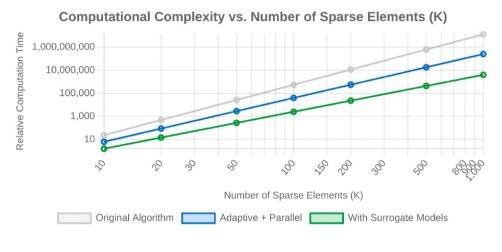
# **EPFL** Hybrid Quality-Complexity Optimization

#### Key Challenge

- Original algorithm has  $O(K^{4.37})$  complexity
- Hard trade-off between denoising and caching
- Bottleneck for large-scale problems
   (e.g., cryo-EM with K > 1000)

#### Adaptive Denoising/Caching Strategy

- Dynamic decision mechanism based on:
- Real-time noise estimates
- Iteration number (early vs. late)
- Available computational budget
- Prioritizes denoising when noise is high
- Favors caching when noise is low









# **OVERVIEW**

- 1. Albert Cohen
- 2. Our 2019 paper revisited
- 3. Super Resolution phase retrieval for sparse signals
- 4. Where to go from here
- 4. Conclusion

# **EPFL** Concluding words

- 1. Will Al replace researchers?
- 2. I trust my (former) graduate students, not sure about Al...
- 3. It is like driving a Ferrari... without the hands on the wheel!
- 4. Is Al simply averaging what is out there (reversal to the mean)?
- 5. I still believe in originality, but then....
- 6. Epistemology of AI?

Fortunately there are deep thinkers like Albert Cohen...

Thank you Albert for all your contributions and friendship!



# Thanks to ...

... the **organisers** for inviting me.

... my coauthors Gilles Baechler, Miranda Krekovic, Juri Ranieri, Amina Chebira, and Yue M. Lu

... Support by ERC and Swiss NSF Grant,

# **EPFL**



 École polytechnique fédérale de Lausanne