

Three inequalities for sampling numbers

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Nonlinear Approximation for High-Dimensional Problems.

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The problem of sampling recovery

Given: A domain D and a function $f: D \rightarrow \mathbb{C}$.

Task: Find a good approximation of f . The error is measured in $L_p(\mu)$ for some p and μ .

Problem: We **do not know** f and can only obtain samples $f(x_1), \dots, f(x_m)$. Each sample is costly!

- What are good sampling points? What is the best we can do with m samples?

This question only make sense if we have some **a priori knowledge** about f (smoothness, structure, ...). The **model class** F is the class of all functions that satisfy the a priori knowledge.

Sampling numbers

We want to study the worst-case error of the **best possible algorithm** that uses at most m samples:

$$g_m(F, L_p) := \underbrace{\inf_{\substack{x_1, \dots, x_m \in D \\ \Phi: \mathbb{C}^m \rightarrow L_p}} \sup_{f \in F} \left\| f - \underbrace{\underbrace{\Phi}_{\text{recovery map}} \underbrace{(f(x_1), \dots, f(x_m))}_{\text{samples}}} \right\|_p}_{\substack{\text{approximation error in } L_p(\mu) \\ \text{worst case over the model class}}}.$$

worst case error of **best sampling algorithm**

What model classes F do we consider?

- ▶ There are many results for particular (smoothness) classes F : Sobolev, Korobov, Gaussian, Hölder, Wiener, Besov, ...
- ▶ We do not want to consider specific classes, but rather study general relations to other approximation benchmarks.
- ▶ We discuss three different approaches.
- ▶ All three approaches work nicely if:

Global assumption

Let D be a compact metric space, μ a Borel probability measure, and F a compact subset of $C(D)$, the space of continuous functions.

1. Comparison with best uniform approximation

The n -th **Kolmogorov number** of F in $C(D)$ is

$$d_n(F, C(D)) := \underbrace{\inf_{\substack{V_n \subset C(D) \\ \dim(V_n) = n}} \sup_{f \in F} \underbrace{\inf_{g \in V_n} \|f - g\|_\infty}_{\text{best approximation from } V_n}}_{\text{best approximation space } V_n}.$$

- ▶ It describes the best uniform approximation of F by an n -dimensional space.
- ▶ By the compactness, we have $\lim_{n \rightarrow \infty} d_n(F, C(D)) = 0$.

Theorem 1

For any D , μ and F ,

$$g_{4n}(F, L_p(\mu)) \leq 6 \cdot n^{(1/2-1/p)+} \cdot d_n(F, C(D)).$$

Remark (references)

The case $p = 2$ was obtained by [V. Temlayakov](#) (JoC, 2021).

The case for general p is joint work with [K. Pozharska](#), [M. Ullrich](#), and [T. Ullrich](#) (JMAA, to appear).

Constants: work in progress with [M. Dolbeault](#) and [M. Ullrich](#).

Theorem 1

For any D , μ and F ,

$$g_{4n}(F, L_p(\mu)) \leq 6 \cdot n^{(1/2-1/p)_+} \cdot d_n(F, C(D)).$$

Remark (local version)

In fact, for any space $V_n \subset C(D)$, we find a plain least-squares estimator $\hat{f} := \operatorname{argmin}_{g \in V_n} \sum_{i=1}^{4n} |g(x_i) - f(x_i)|^2$ such that

$$\forall f \in C(D): \quad \|f - \hat{f}\|_p \leq 6 \cdot n^{(1/2-1/p)_+} \cdot \inf_{g \in V_n} \|f - g\|_\infty.$$

Theorem 1

For any D , μ and F ,

$$g_{4n}(F, L_p(\mu)) \leq 6 \cdot n^{(1/2-1/p)+} \cdot d_n(F, C(D)).$$

Remark (sharpness)

In general, the bound cannot be improved:

If F is the unit ball of the Sobolev space $W_1^s[0, 1]$ (for $p \geq 2$) or $W_\infty^s[0, 1]$ (for $p \leq 2$), then

$$g_n(F, L_p(\mu)) \asymp n^{(1/2-1/p)+} \cdot d_n(F, C(D)).$$

Theorem 1

For any D , μ and F ,

$$g_{2n}(F, C(D)) \leq 4\sqrt{n} \cdot d_n(F, C(D)).$$

Remark (related bounds for $p = \infty$)

Two related bounds by E. Novak (Springer Lecture Notes, 1988) and B. Kashin, S. Konyagin, V. Temlyakov (CA, 2023):

$$g_n(F, C(D)) \leq (n + 1) \cdot d_n(F, C(D))$$

$$g_{9n}(F, C(D)) \leq 5 \cdot d_n(F, C(D))$$

2. Comparison with best L_2 -approximation

The n -th **Kolmogorov number** of F in $L_2(\mu)$ is

$$d_n(F, L_2(\mu)) := \underbrace{\inf_{\substack{V_n \subset C(D) \\ \dim(V_n)=n}} \sup_{f \in F} \underbrace{\inf_{g \in V_n} \|f - g\|_2}_{\text{best approximation from } V_n}}_{\text{worst case over model class}} \quad .$$

best approximation space V_n

- It describes the best $L_2(\mu)$ approximation of F by an n -dimensional space. We could restrict to **linear approximation** (the best approximation is given by the orthogonal projection).

Theorem 2

For any D , μ and F ,

$$g_{8n}(F, L_2) \leq \frac{20}{\sqrt{n}} \cdot \sum_{k \geq n} \frac{d_k(F, L_2)}{\sqrt{k}}.$$

Remark (references)

The result is basically from joint work with [M. Dolbeault](#) and [M. Ullrich](#) (ACHA, 2023).

Small improvement in a paper with [K. Pozharska](#), [M. Ullrich](#), and [T. Ullrich](#) (preprint).

Constants: work in progress with [M. Dolbeault](#) and [M. Ullrich](#).

Theorem 2

For any D , μ and F ,

$$g_{8n}(F, L_2) \leq \frac{20}{\sqrt{n}} \cdot \sum_{k \geq n} \frac{d_k(F, L_2)}{\sqrt{k}}.$$

Remark (tractability)

Requires

$$R := \sum_{k=1}^{\infty} \frac{d_k(F, L_2)}{\sqrt{k}} < \infty.$$

But then already a simplified formula can be useful in **high dimensions**:

$$g_{8n}(F, L_2(D)) \leq 20R \cdot n^{-1/2}.$$

Theorem 2

For any D , μ and F ,

$$g_{8n}(F, L_2) \leq \frac{20}{\sqrt{n}} \cdot \sum_{k \geq n} \frac{d_k(F, L_2)}{\sqrt{k}}.$$

Remark (convergence rates)

In particular, if $d_n(F, L_2) \lesssim n^{-s} \log^r n$, then

$$g_n(F, L_2) \lesssim \begin{cases} n^{-s} \log^r n & \text{if } s > 1/2, \\ n^{-s} \log^{r+1} n & \text{if } s = 1/2 \text{ and } r < -1, \\ 1 & \text{otherwise.} \end{cases}$$

Moreover, there exist classes F such that these bounds are sharp.

Theorem 2

For any D , μ and F ,

$$g_{8n}(F, L_2) \leq \frac{20}{\sqrt{n}} \cdot \sum_{k \geq n} \frac{d_k(F, L_2)}{\sqrt{k}}.$$

Remark (other approximation spaces)

In fact, for any sequence of nested approximation spaces $(V_n)_{n \in \mathbb{N}}$, we find a weighted least squares estimator

$$\hat{f} := \operatorname{argmin}_{g \in V_n} \sum_{i=1}^{8n} w_i |g(x_i) - f(x_i)|^2 \quad \text{s.t.}$$

$$\forall f \in F: \quad \|f - \hat{f}\|_p \leq \frac{20}{\sqrt{n}} \cdot \sum_{k \geq n} k^{-1/2} \left(\sup_{f \in F} \operatorname{dist}_2(f, V_n) \right).$$

Theorem 2

For any D , μ and F ,

$$g_{8n}(F, L_2) \leq \frac{20}{\sqrt{n}} \cdot \sum_{k \geq n} \frac{d_k(F, L_2)}{\sqrt{k}}.$$

Remark (Hilbert case)

There is a slightly better formula for Hilbert spaces (see ACHA):

$$g_{4n}(F, L_2) \leq \frac{12}{\sqrt{n}} \cdot \sqrt{\sum_{k \geq n} d_k(F, L_2)^2}.$$

This bound is sharp up to the constants for any possible sequence of Kolmogorov numbers (joint work with [J. Vybíral](#) (JFAA, 2023)).

Theorem 2

For any D , μ and F ,

$$g_{8n}(F, L_2) \leq \frac{20}{\sqrt{n}} \cdot \sum_{k \geq n} \frac{d_k(F, L_2)}{\sqrt{k}}.$$

Remark ($p \neq 2$)

If the approximation spaces are “nice enough”, this can be turned into a bound for [sampling numbers in \$L_p\(\mu\)\$](#) or other error norms (see preprint with [K. Pozharska](#), [M. Ullrich](#), and [T. Ullrich](#)). “Nice enough” means a good behavior of

$$\Lambda_n := \sup_{f \in V_n \setminus \{0\}} \frac{\|f\|_p}{\|f\|_2}.$$

Theorem 2

For any D , μ and F ,

$$g_{8n}(F, L_2) \leq \frac{20}{\sqrt{n}} \cdot \sum_{k \geq n} \frac{d_k(F, L_2)}{\sqrt{k}}.$$

Remark (randomized algorithms)

The expected error of randomized algorithm behaves even nicer. Here we have

$$g_{2n}^{\text{ran}}(F, L_2) \leq 4 d_n(F, L_2).$$

See the papers by [A. Cohen and M. Dolbeault](#) (JoC, 2022) and [A. Chkifa and M. Dolbeault](#) (SIAM JoNA, 2024).

3. Comparison with best sparse approximation

Let \mathcal{B} be a finite orthonormal system in $L_2(\mu)$ which consists of bounded functions and let

$$\Sigma_n(\mathcal{B}) := \bigcup_{b_1, \dots, b_n \in \mathcal{B}} \text{Span}\{b_1, \dots, b_n\}.$$

The **best n -term widths** of F w.r.t. \mathcal{B} are defined by

$$\sigma_n(F, \mathcal{B}) := \sup_{f \in F} \underbrace{\inf_{g \in \Sigma_n(\mathcal{B})} \|f - g\|_\infty}_{\substack{\text{best } n\text{-sparse approximation} \\ \text{worst case over model class}}}.$$

Theorem 3

For any $n \geq 2 \max_{b \in \mathcal{B}} \|b\|_\infty^2$, we have

$$g_{m(n)}(F, L_p(\mu)) \leq C \cdot n^{(1/2-1/p)_+} \cdot \sigma_n(F, \mathcal{B}).$$

where $m(n) := Cn \log^3(n) \log(\#\mathcal{B})$.

Remarks

Note the similarity to Theorem 1 for the special case $\#\mathcal{B} = n$, where $\sigma_n(F, \mathcal{B}) = d_n(F, \text{Span}(\mathcal{B}))$.

Because of the **condition on n** , the bound is only useful for special orthonormal systems (like Fourier or Walsh functions). The constant C is universal.

Theorem 3

For any $n \geq 2 \max_{b \in \mathcal{B}} \|b\|_\infty^2$, we have

$$g_{m(n)}(F, L_p(\mu)) \leq C \cdot n^{(1/2-1/p)_+} \cdot \sigma_n(F, \mathcal{B}).$$

where $m(n) := Cn \log^3(n) \log(\#\mathcal{B})$.

Remarks (reference)

The bound follows from classical compressed sensing algorithms (ℓ_1 -minimization, square-root lasso) and their analysis, for instance, [Rauhut & Ward \(2016\)](#).

We only reinterpret the samples $f(x_i)$, $f \in F$, as noisy samples of the sparse function $g(x_i)$, $g \in \Sigma_n$.

Theorem 3

For any $n \geq 2 \max_{b \in \mathcal{B}} \|b\|_\infty^2$, we have

$$g_{m(n)}(F, L_p(\mu)) \leq C \cdot n^{(1/2-1/p)_+} \cdot \sigma_n(F, \mathcal{B}).$$

where $m(n) := Cn \log^3(n) \log(\#\mathcal{B})$.

Remarks (linear vs. nonlinear)

The approach was used by [T. Jahn](#), [T. Ullrich](#) and [F. Voigtlaender](#) (JoC, 2023) to obtain new asymptotic bounds for the sampling numbers $W_p^{s, \text{mix}}([0, 1]^d)$, $p < 2$.

Any linear algorithm has a worse order of convergence.

Theorem 3

For any $n \geq 2 \max_{b \in \mathcal{B}} \|b\|_\infty^2$, we have

$$g_{m(n)}(F, L_p(\mu)) \leq C \cdot n^{(1/2-1/p)_+} \cdot \sigma_n(F, \mathcal{B}).$$

where $m(n) := Cn \log^3(n) \log(\#\mathcal{B})$.

Remarks (linear vs. nonlinear)

The approach was used by K. (PAMS, 2024) to obtain tractability results for L_p -approximation in Wiener-type function classes, e.g., the unit ball of

$$C^\alpha(\mathbb{T}^d) \cap \mathcal{A}(\mathbb{T}^d).$$

All **linear algorithms suffer from the curse** of dimensions.

Thank you for your attention!